

First Order Hamiltonian perturbation theory

We transform

$$H(\underline{I}, \underline{\theta}) = H_0(\underline{I}) + \epsilon H_1(\underline{I}, \underline{\theta}) + O(\epsilon^2)$$

$$\bar{H}(\bar{\underline{I}}, \bar{\underline{\theta}}) = \bar{H}_0(\bar{\underline{I}}) + \epsilon \bar{H}_1(\bar{\underline{I}}) + O(\epsilon^2)$$

$$(\underline{I}, \underline{\theta}) \rightarrow (\bar{\underline{I}}, \bar{\underline{\theta}})$$

$$S(\bar{\underline{I}}, \bar{\underline{\theta}}) = \bar{\underline{I}} \cdot \bar{\underline{\theta}} + \epsilon S_1(\bar{\underline{I}}, \bar{\underline{\theta}}) + O(\epsilon^2)$$

$$H_1(\underline{I}, \underline{\theta}) = H_{10}(\underline{I}) + \sum_{\underline{m} \neq 0} H_{1\underline{m}}(\underline{I}) e^{i\underline{m} \cdot \underline{\theta}}$$

$$\underline{\omega}_0(\bar{\underline{I}}) \cdot \frac{\partial S_1}{\partial \bar{\underline{\theta}}}(\bar{\underline{I}}, \bar{\underline{\theta}}) = - \sum_{\underline{m} \neq 0} H_{1\underline{m}}(\bar{\underline{I}}) e^{i\underline{m} \cdot \bar{\underline{\theta}}}$$

Pendulum

$$H_2 = \omega_0 I - \frac{\epsilon}{48} I^2 (3 - 4 \cos 2\theta + \cos 4\theta) + O(\epsilon^2)$$

$$(*) \quad \omega_0 \frac{\partial S_1}{\partial \theta} = \frac{\bar{I}^2}{48} (-4 \cos 2\bar{\theta} + \cos 4\bar{\theta})$$

$$\bar{H}_0(\bar{I}) = H_0(\bar{I}) = \omega_0 \bar{I}$$

$$\begin{aligned} \bar{H}_1(\bar{I}, \bar{\theta}) &= -\frac{\bar{I}^2}{48} (3 - 4 \cos 2\bar{\theta} + \cos 4\bar{\theta}) \\ &+ \omega_0 \frac{\partial S_1}{\partial \theta}(\bar{I}, \bar{\theta}) \end{aligned}$$

new Hamiltonian

$$\bar{H}(\bar{I}) = \omega_0 \bar{I} - \epsilon \frac{\bar{I}^2}{16} + O(\epsilon^2)$$

$$\begin{aligned} \Rightarrow \bar{I} &= O(\epsilon^2) \\ \dot{\bar{\theta}} &= \omega_0 - \frac{\epsilon \bar{I}}{8} + O(\epsilon^2) = \omega_0 I \end{aligned}$$

Lie perturbative theory (time-independent case)

Consider a canonical transformation

$\bar{x} = \bar{x}(\bar{z})$ Associative with Z is
a transformation

operator T

$$(TF)(\bar{z}) = F(Z(z))$$

$$T\dot{z} = \dot{Z}(z) = \dot{z}$$

$$\bar{z} = (q, p)$$

In particular

$$K(\bar{z}) = K(Z(z)) = H(z)$$

$$K(\bar{z}) = H(Z^{-1}(\bar{z}))$$

$$K = T^{-1}H (*)$$

The canonical transformation

is generated by

Infinitesimal canonical transformation

generated by generator $G(z, \varepsilon)$

In terms of G

$$T = \exp - \int d\varepsilon L_G$$

$$L_G = \{G, F\}$$

Suppose

$$G(z, \varepsilon) = G_1(z) + \varepsilon G_2(z) + \varepsilon^2 G_3(z)$$

$$Lg_i = \bar{L}_i$$

$$T = 1 + \epsilon L_1 + \frac{1}{2} \epsilon^2 (L_2 + L_1^2) + O(\epsilon^3)$$

$$T^{-1} = 1 + \epsilon L_1 + \frac{1}{2} \epsilon^2 (L_2 + L_1^2) + O(\epsilon^3)$$

$$\text{Suppose } K = \sum_{n=0}^{\infty} \epsilon^n K_n$$

$$H = \sum_{n=0}^{\infty} \epsilon^n H_n$$

and substitute T^{-1} into $K = T^{-1}H$

$$O(\epsilon^0) \quad K_0 = H_0$$

$$K_0(\bar{z}) = H_0(\bar{z})$$

$$O(\epsilon^1) \quad K_1 = H_1 + L_1 H_0$$

$$O(\epsilon^2) \quad K_2 = H_2 + L_1 H_1 + \frac{1}{2} (L_2 + L_1^2) H_0$$

$$O(\epsilon^0) \quad K_0(\bar{z}) = H_0(\bar{z})$$

$$O(\epsilon^1) \quad L_1 H_0 = \{G_1, H_0\} = \left(\frac{\partial G_1}{\partial \bar{z}} \right)^T \underline{J} \cdot \frac{\partial H_0}{\partial \bar{z}} \equiv D_0 G_1$$

$$\text{(where } D_0 G_1 = \frac{\partial G_1}{\partial t} + \{G_1, H_0\} \text{)}$$

$$\bar{q} = \{q, H\} \quad \bar{p} = \{p, H\}$$

D_0 time derivative

$$O(\epsilon^0) \quad 0 = K_0 - H_0$$

$$O(\epsilon) \quad D_0 G_1 = K_1 - H_1$$

$$O(\epsilon^2) \quad D_0 G_2 = Z(K_2 - H_2) - L_1(H_1 + K_1)$$

ie $D_0 G_1 = K_1 - H_1$ is a
differential eq. for G_1 and K_1

Similarly

Example: Pendulum Problem

$$H_\epsilon(I, \theta) = H_0 + \epsilon H_1 + O(\epsilon^2)$$

$$H_0(I, \theta) = \omega_0 I$$

$$H_1(I, \theta) = -\frac{1}{4g} I^2 (3 - 4 \cos 2\theta + \cos 4\theta)$$

$$O(\epsilon^0) = K_0(I) = \omega_0 I$$

$$O(\epsilon^1) = K_1 = H_1 + D_0 G = H_1 + \{G_1, H_0\} = H_1 + \omega_0 \frac{\partial G_1}{\partial \theta}$$

$$\omega_0 \frac{\partial G_1}{\partial \theta} = K_1 - H_1 \quad \text{Suppose we try } K_1 = 0$$

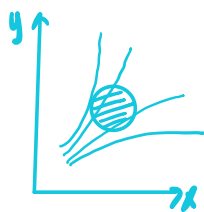
$$A^M = \begin{pmatrix} \phi \\ \bar{A} \end{pmatrix}$$

$$F^{M\nu} = \partial^M A^\nu - \partial^\nu A^M = \begin{pmatrix} 0 & E^j \\ -E^i & e^{ijk} B^k \end{pmatrix}$$

$$\frac{dP^M}{dz} = q F^{M\nu} u_\nu$$

$$u^{\nu'} = \begin{pmatrix} \gamma \\ \gamma \bar{v} \end{pmatrix}$$

Fluid



$S_V(x)$

$N_i(x)$

$P(x)$

$\bar{v}(x)$

$T(x)$

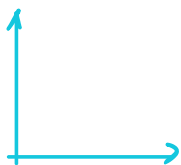
$$n_i(x) = \frac{N_i}{S_V}$$

i carry q_i

$$P(x) = n_i(x) q_i$$

$$\rho = \sum_i \rho_i = \sum_i n_i q_i$$

$$\bar{J}(x) = \rho \bar{v} = \sum_i n_i q_i \bar{v}$$



$$Q = \int_V \rho a^3 dx$$